

JV241010

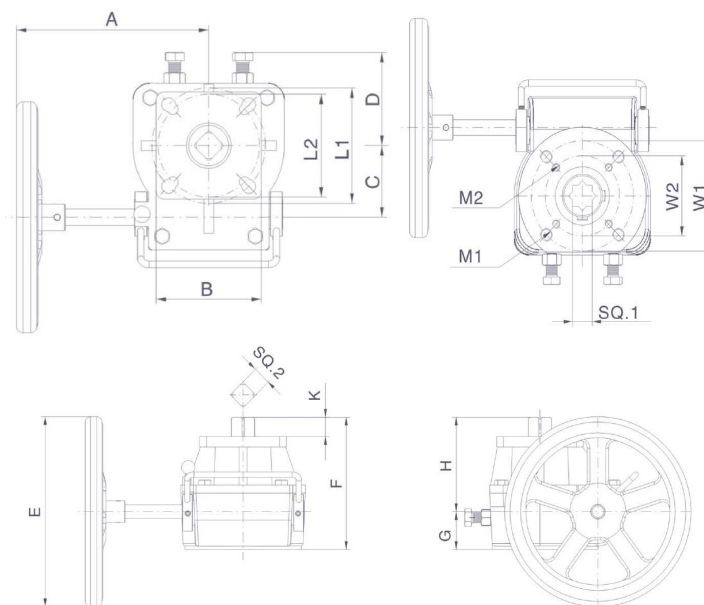
**De-Clutchable Gearbox
with Manual Override
for
Pneumatic Actuators**



The JV241010 worm gear gearbox is designed to sandwich in-between a valve and pneumatic actuator to provide manual operation of the valve in the event of a loss of control air supply.

The gearbox has an ISO 5211 interface and has a body constructed of aluminium alloy.

Model	Output Torque	Speed Ratio
JV241010-1	180	26:1
JV241010-2	320	28:1
JV241010-3	380	38:1
JV241010-4	1200	54:1
JV241010-5	2100	80:1
JV241010-6	3000	78:1
JV241010-7	3800	98:1



Model	JV241010-1	JV241010-2	JV241010-3	JV241010-4	JV241010-5	JV241010-6	JV241010-7
A	150	170	200	260	310	395	435
B	70	95	115	140	155	160	235
C	50	55	82	85	125	140	170
D	43	65	90	102	110	140	160
E	180	200	280	320	400	500	600
F	120	127	152	193	223	248	248
G	35	40	40	60	55	60	60
H	85	87	110	135	154	172	183
K	15	19	22	28	39	48	55
M1	M8x4	M10x4	M12x4	M16x4	M20x4	M20x4	M20x4
M2	M6x4	M8x4	M10x4	M10x4/M12x4	M16x4	M16x4	-
W1	F07	F10	F12	F14	F16	F16	F16
W2	F05	F07	F10	F10 (F12 option)	F14	F14	-
SQ.1	14	17	22	27	36	46	46
L1	F07	F10	F12	F14	F16	F16	F16
L2	F05	F07	F10	F12	F14	-	-
SQ.2	14	17	22	27	36	46	46
Weight Kg	3	4.5	7	13.7	22	30	38